

# Distributed System Development with ScalaLoci

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# Flink



```
class TaskManagerGateway {
  def connectFromJobManager(instanceId: InstanceID, cause: Exception, mgr: ActorRef) = {
    mgr ! connect(instanceId, cause)
  }

  def stopCluster(applicationStatus: ApplicationStatus, message: String, mgr: ActorRef) = {
    mgr ! stopCluster(applicationStatus, message)
  }

  def submitTask(tdd: TaskDeploymentDescriptor, mgr: ActorRef) = {
    (mgr ? submitTask(tdd)).mapTo[StackTrace]
  }

  def cancelTask(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    (mgr ? cancelTask(executionAttemptID)).mapTo[StackTrace]
  }

  def cancelTask(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    (mgr ? cancelTask(executionAttemptID)).mapTo[StackTrace]
  }

  def partitionInfos(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    (mgr ? partitionInfos(executionAttemptID)).mapTo[Iterable[PartitionInfo]]
  }

  def triggerCheckpoint(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    (mgr ? triggerCheckpoint(executionAttemptID)).mapTo[StackTrace]
  }

  def requestTaskManagerLog(logTypeRequest: LogTypeRequest, mgr: ActorRef) = {
    (mgr ? requestTaskManagerLog(logTypeRequest)).mapTo[BlobKey]
  }
}
```

```
class TaskManager extends Actor {
  def receive = {
    case StackTrace => sendStackTrace() foreach { message =>
      sender ! decorateMessage(message)
    }
    case Disconnect(instanceIdToDisconnect, cause) => {
      if (instanceIdToDisconnect.equals(instanceId)) {
        handleJobManagerDisconnect("JobManager requested disconnect: " +
          cause.getMessage())
        triggerTaskManagerRegistration()
      } else {
        log.debug("Received disconnect message for wrong instance id " +
          instanceIdToDisconnect)
      }
    }
    case StopCluster(applicationStatus, message) => {
      log.info(s"Stopping TaskManager with final application status " +
        s"$applicationStatus and diagnostics: $message")
      shutdown()
    }
    case RequestTaskManagerLog(requestType) => {
      blobService match {
        case Some(s) => {
          handleRequestTaskManagerLog(requestType, currentJobManager.get) match {
            case Left(message) => sender ! decorateMessage(message)
            case Right(message) => sender ! decorateMessage(message)
          }
        }
        case None => {
          sender ! akka.actor.Status.Failure(new IOException(
            "BlobService is not available. Cannot upload TaskManager logs."))
        }
      }
    }
    case UpdatePartitionInfos(executionID, partitionInfos) => {
      log.info(s"Updating partition infos for task execution $executionID")
      try {
        network.getResultPartitionManager.releasePartitionsProducedBy(executionID)
      } catch {
        case t: Throwable => killTaskManagerFatal(
          s"Fatal task: Unable to release intermediate result partition data", t)
      }
    }
    case SubmitTask(tdd) => {
      sender ! decorateMessage(submitTask(tdd))
    }
    case StopTask(executionID) => {
      val task = runningTasks.get(executionID)
      if (task != null) {
        task.stop()
        sender ! decorateMessage(Acknowledge.get())
      } else {
        sender ! decorateMessage(Status.Failure(t))
      }
    }
    case CancelTask(executionID) => {
      val task = runningTasks.get(executionID)
      if (task != null) {
        task.cancel()
        sender ! decorateMessage(Acknowledge.get())
      } else {
        sender ! decorateMessage(Status.Failure(t))
      }
    }
    case TriggerCheckpoint(jobId, taskExecutionId, checkpointId, timestamp,
      checkpointOptions) => {
      log.debug(s"Receiver triggerCheckpoint $checkpointId@$timestamp " +
        s"for $taskExecutionId")
      val task = runningTasks.get(taskExecutionId)
      if (task != null) {
        task.triggerCheckpointBarrier(checkpointId, timestamp, checkpointOptions)
      } else {
        log.debug(s"TaskManager received a checkpoint request " +
          s"for unknown task $taskExecutionId")
      }
    }
    case NotifyCheckpointComplete(jobId, taskExecutionId, checkpointId, timestamp) => {
      log.debug(s"Receiver ConfirmCheckpoint $checkpointId@$timestamp " +
        s"for $taskExecutionId")
      val task = runningTasks.get(taskExecutionId)
      if (task != null) {
        task.notifyCheckpointComplete(checkpointId)
      } else {
        log.debug(s"TaskManager received a checkpoint confirmation " +
          s"for unknown task $taskExecutionId")
      }
    }
  }
}
```

# Multitier Languages

## Single Compilation Unit

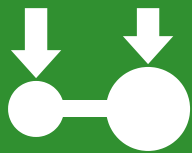


# ScalaLoci

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Generic Distributed Architectures



Placement Types



Multitier Event Streams

# Placement Types

---

```
trait Registry extends Peer  
trait Node extends Peer
```

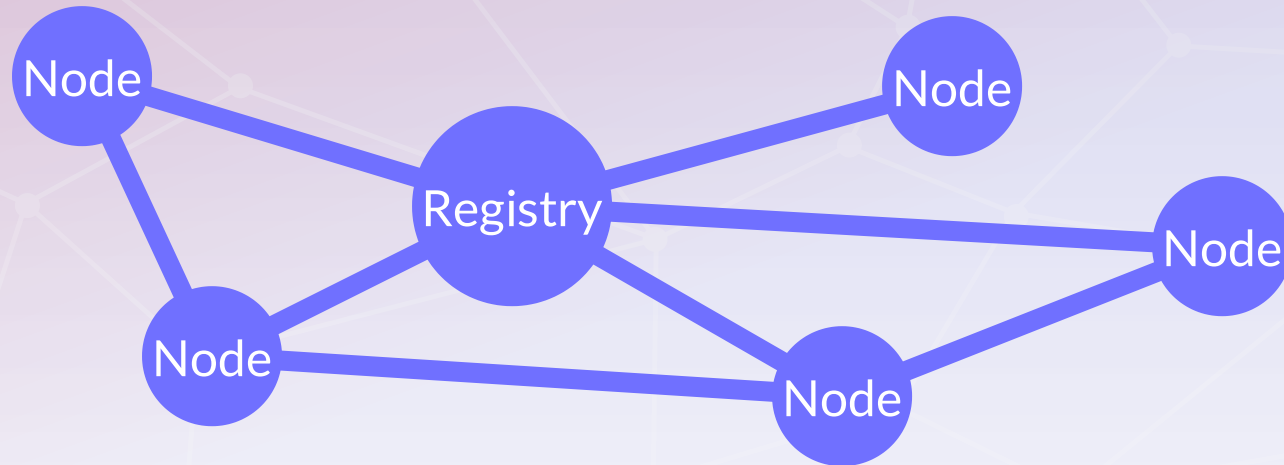
Peers

```
val message: Event[String] on Registry  
= placed { getMessageStream() }
```

Placement  
Types

# Architecture

```
trait Registry extends Peer { type Tie <: Multiple[Node] }  
trait Node extends Peer { type Tie <: Single[Registry] with Multiple[Node] }
```



Architecture Specification  
through Peer Types

Architecture-Based  
Remote Access

# Remote Access

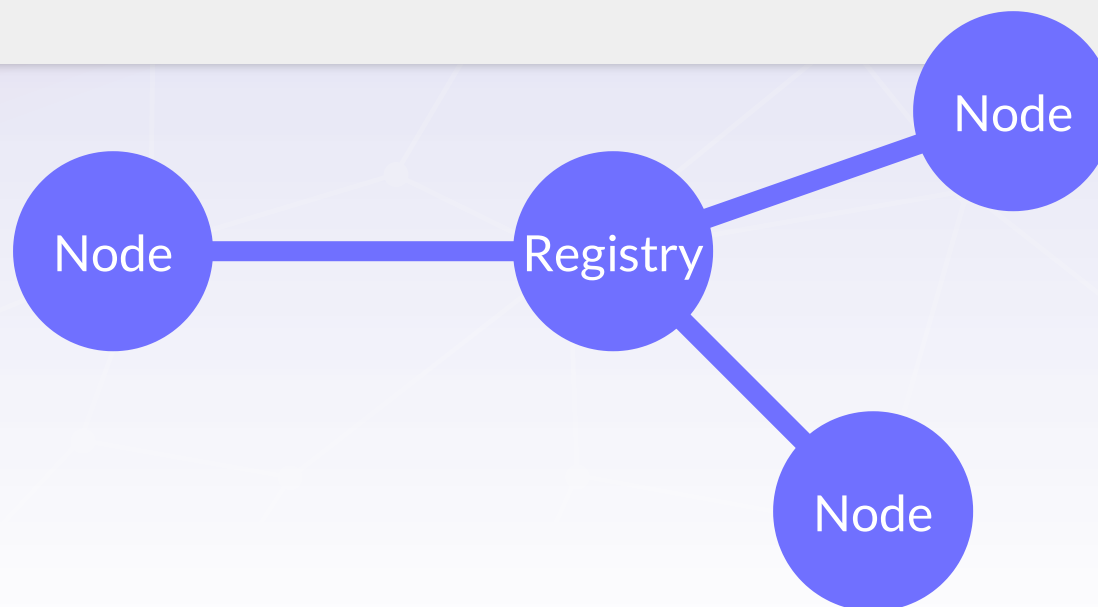
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```
trait Registry extends Peer { type Tie <: Single[Node] }  
trait Node extends Peer { type Tie <: Single[Registry] }  
  
val message: Event[String] on Node  
  
placed[Registry] {  
  message.asLocal: Event[String]  
}
```



# Aggregation

```
trait Registry extends Peer { type Tie <: Multiple[Node] }  
trait Node extends Peer { type Tie <: Single[Registry] }  
  
val message: Event[String] on Node  
  
placed[Registry] {  
  message.asLocalFromAll: Map[Remote[Node], Event[String]]  
}
```





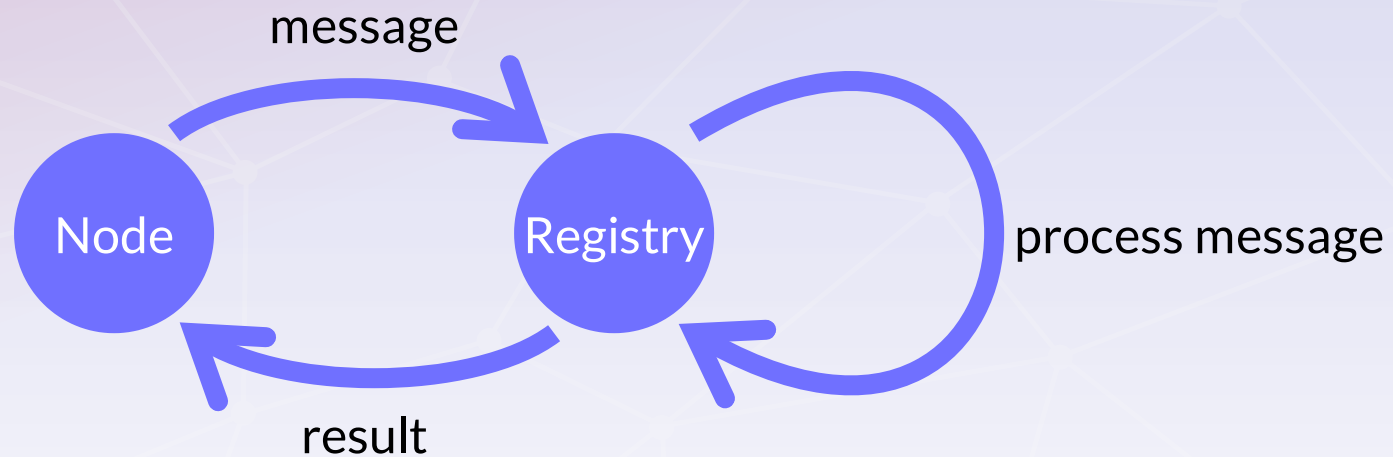
# Communication

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# Data Flow

```
val message = Event[String]()  
val result = message map processMessage  
val ui = new UI(result)
```



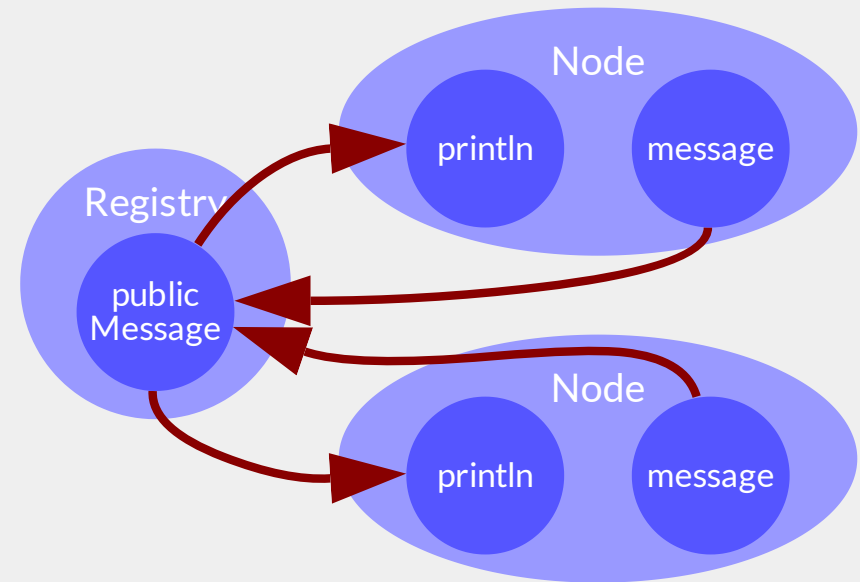
# Distributed Data Flow

```
val message: Event[String] on Node = placed[Node] { Event[String]() }  
val result = placed[Registry] { message.asLocal map processMessage }  
val ui = placed[Node] { new UI(result.asLocal) }
```



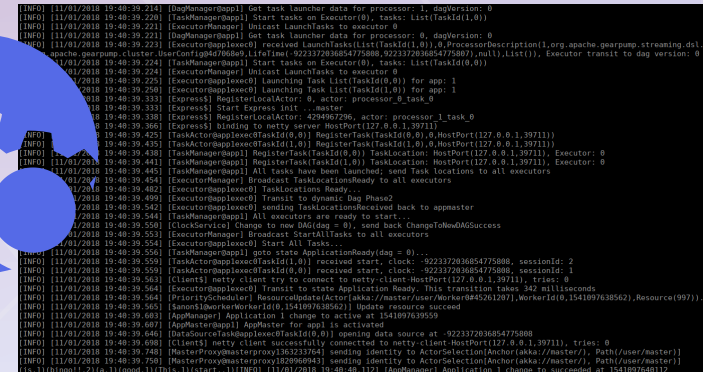
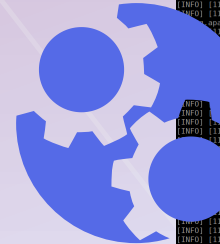
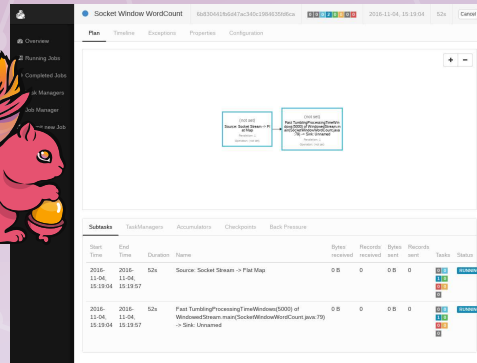
# Complete Distributed Chat

```
@multitier object Chat {  
  trait Registry extends Peer { type Tie <: Multiple[Node] }  
  trait Node extends Peer { type Tie <: Single[Registry] }  
  
  val message = placed[Node] { Event[String]() }  
  
  val publicMessage = placed[Registry] {  
    message.asLocalFromAllSeq map { case (_, msg) => msg }  
  }  
  
  placed[Node].main {  
    publicMessage.asLocal observe println  
    for (line <- io.Source.stdin.getLines)  
      message.fire(line)  
  }  
}
```

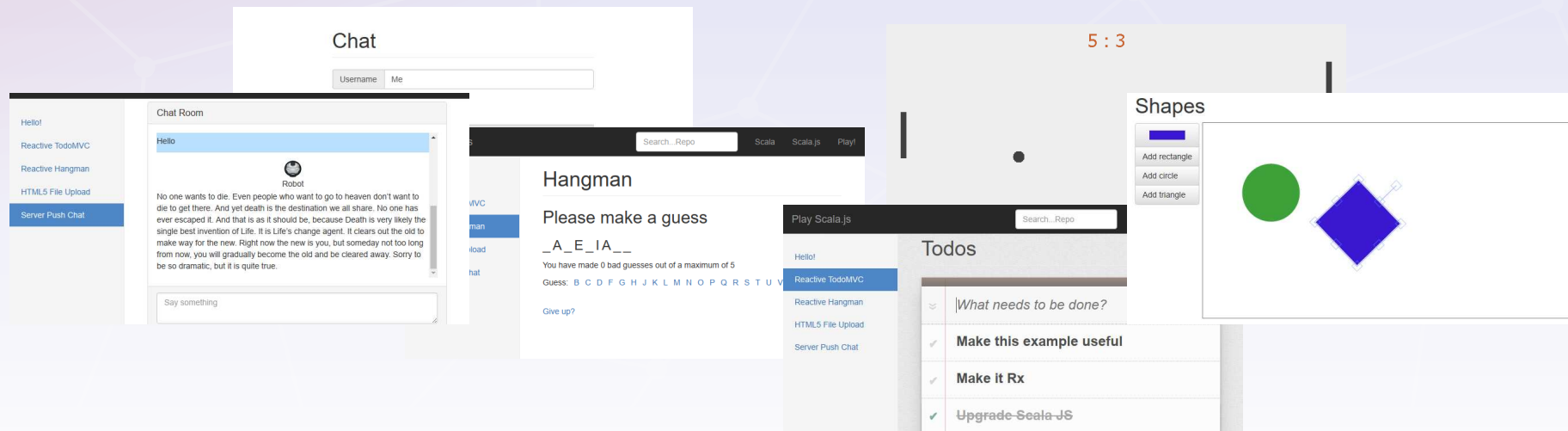


# Evaluation

## Two existing systems



## Case studies: 22 variants



# Porting to Distribution

## Local

```
val ballSize = 20
val maxX = 800
val maxY = 400
val leftPos = 30
val rightPos = 770
val initPosition = Point(480, 200)
val initSpeed = Point(10, 8)
```

```
val ball: Signal[Point] = tick.fold(initPosition) {
  (ball, _) => ball + speed.get }
```

```
val areas = {
  val racketY = Seq(
    Signal { UI.mousePosition().y },
    Signal { ball().y })
  val leftRacket = Racket(leftRacketPos, racketY(0))
  val rightRacket = Racket(rightRacketPos, racketY(1))
  val rackets = List(leftRacket, rightRacket)
  Signal { rackets map { _.area() } }
```

```
val leftWall = ball.changed && { _.x < 0 }
val rightWall = ball.changed && { _.x > maxX }
```

```
val xBounce = {
  val ballInRacket = Signal { areas() exists { _ contains ball() } }
  val collisionRacket = ballInRacket.changedTo True
  leftWall || rightWall || collisionRacket
  val yBounce = ball.changed &&
    { ball => ball.y < 0 || ball.y > maxY }
```

```
val speed = {
  val x = xBounce.toggle (initSpeed.x, -initSpeed.x)
  val y = yBounce.toggle (initSpeed.y, -initSpeed.y)
  Signal { Point(x(), y()) }
```

```
val score = {
  val leftPoints = rightWall.iterate(0) { _, +1 }
  val rightPoints = leftWall.iterate(0) { _, +1 }
  Signal { leftPoints() + "-" + rightPoints() }
```

```
val ui = new UI(areas, ball, score)
```

```
trait Server extends ActorSelection[Client]
trait Client extends ClientActor[Server]
```

```
val ballSize = 20
val maxX = 800
val maxY = 400
val leftPos = 30
val rightPos = 770
val initPosition = Point(480, 200)
val initSpeed = Point(10, 8)
```

```
val clientMouseY = UI.mousePosition() {
  Signal { UI.mousePosition().y } }
val isPlaying = UI.isPlaying() {
  Signal { UI.isPlaying().connected().size > 2 } }
```

```
val ball: Signal[Point] = Server {
  tick.fold(initPosition) { (ball, _) =>
    if (isPlaying.get) ball + speed.get else pos }
```

```
val players = UI.players() {
  Signal {
    UI.players().connected()
    case Seq(left, right) => Seq(Some(left), Some(right))
    case _ => Seq(None, None) } }
```

```
val areas = UI.areas() {
  Signal {
    UI.areas().connected()
    client => (clientMouseY, client) => (()) getOrElse
      initPosition.y } }
```

```
val leftWall = UI.leftWall() {
  Signal { ball.changed && { _.x < 0 } }
  val rightWall = UI.rightWall() {
    ball.changed && { _.x > maxX } }
```

```
val xBounce = UI.xBounce() {
  Signal {
    ballInRacket => Signal { areas() exists { _ contains ball() } }
    val collisionRacket = ballInRacket.changedTo True
    leftWall || rightWall || collisionRacket
    val yBounce = UI.yBounce() {
      ball.changed &&
        { ball => ball.y < 0 || ball.y > maxY }
```

```
val speed = UI.speed() {
  Signal {
    val x = xBounce.toggle (initSpeed.x, -initSpeed.x)
    val y = yBounce.toggle (initSpeed.y, -initSpeed.y)
    Signal { Point(x(), y()) }
```

```
val score = UI.score() {
  Signal {
    val leftPoints = rightWall.iterate(0) { _, +1 }
    val rightPoints = leftWall.iterate(0) { _, +1 }
    Signal { leftPoints() + "-" + rightPoints() }
```

```
val ui = UI(ui) {
  new UI(areas, ball, score, score) }
```

## Akka

```
val ballSize = 20
val maxX = 800
val maxY = 400
val leftPos = 30
val rightPos = 770
val initPosition = Point(480, 200)
val initSpeed = Point(10, 8)
```

```
class Server extends Actor {
  def receive = addPlayer orElse mouseChanged
  val clients = Var[Seq.empty[ActorRef]]
  val mousePositions = Var[Map.empty[ActorRef, Int]]
  def mouseChanged: Receive = { case MouseChanged(y) =>
    mousePositions transform { (_, sender) => y } }
  val isPlaying = Signal { clients().size >= 2 }
```

```
val ball: Signal[Point] = { (ball, _) =>
  if (isPlaying.get) ball + speed.get else ball }
```

```
def addPlayer() = {
  clients transform { (_, sender) =>
    sender ! AddPlayer }
```

```
val players = Signal {
  clients() match {
    case Seq(left, right) => Seq(Some(left), Some(right))
    case _ => Seq(None, None) } }
```

```
val areas = {
  val racketY = Signal {
    UI.mousePosition() get _ getOrElse initPosition.y }
  val leftRacket = new Racket(leftPos, racketY(0))
  val rightRacket = new Racket(rightPos, racketY(1))
  val rackets = List(leftRacket, rightRacket)
  Signal { rackets map { _.area() } }
```

```
val leftWall = ball.changed && { _.x < 0 }
val rightWall = ball.changed && { _.x > maxX }
```

```
val xBounce = {
  val ballInRacket = Signal { areas() exists { _ contains ball() } }
  val collisionRacket = ballInRacket.changedTo True
  leftWall || rightWall || collisionRacket
  val yBounce = ball.changed &&
    { ball => ball.y < 0 || ball.y > maxY }
```

```
val speed = {
  val x = xBounce.toggle (Signal { initSpeed.x }, Signal { -initSpeed.x })
  val y = yBounce.toggle (Signal { initSpeed.y }, Signal { -initSpeed.y })
  Signal { Point(x(), y()) }
```

```
val score = {
  val leftPlayerPoints = rightWall.iterate(0) { _, +1 }
  val rightPlayerPoints = leftWall.iterate(0) { _, +1 }
  Signal { leftPlayerPoints() + "-" + rightPlayerPoints() }
```

```
areas observe / areas => clients now foreach { client =>
  ball observe / ball => clients now foreach { client =>
  score observe / score => clients now foreach { client =>
    client ! UpdateScore(score) }
```

```
clients observe / clients =>
  client ! UndataArea(areas.now)
  client ! UndataBall(ball.now)
  client ! UpdateScore(score.now) }
```

```
abstract class Client(server: ActorSelection) extends Actor {
  def ball = UI.ball()
  def score = UI.score()
  def mousePosition observe / pos =>
    server ! MouseChanged(pos.y) }
```

```
val ui = new UI(areas, ball, score)
```

```
def receive = {
  case UndataArea(areas) => UI.areas set areas
  case UndataBall(ball) => UI.ball set ball
  case UpdateScore(score) => UI.score set score }
```

```
server ! AddPlayer
}
```

## RMI

```
val ballSize = 20
val maxX = 800
val maxY = 400
val leftPos = 30
val rightPos = 770
val initPosition = Point(480, 200)
val initSpeed = Point(10, 8)
```

```
object UI {
  def mousePosition = UI.mousePosition() {
    Signal { UI.mousePosition().y } }
  def isPlaying = UI.isPlaying() {
    Signal { UI.isPlaying().connected().size > 2 } }
```

```
class Server extends Actor {
  val clients = Var[Seq.empty[Client]]
  val mousePositions = Var[Map.empty[Client, Int]]
  def mouseChanged: Receive = { case MouseChanged(y) =>
    mousePositions() = mousePositions.get + (client -> y) }
  val isPlaying = Signal { clients().size >= 2 }
```

```
val ball: Signal[Point] = tick.fold(initPosition) { (ball, _) =>
  if (isPlaying.get) ball + speed.get else ball }
```

```
def addPlayer() = {
  clients transform { (_, sender) =>
    sender ! AddPlayer }
```

```
val players = Signal {
  clients() match {
    case Seq(left, right) => Seq(Some(left), Some(right))
    case _ => Seq(None, None) } }
```

```
val areas = {
  val racketY = Signal {
    UI.mousePosition() get _ getOrElse initPosition.y }
  val leftRacket = new Racket(leftPos, racketY(0))
  val rightRacket = new Racket(rightPos, racketY(1))
  val rackets = List(leftRacket, rightRacket)
  Signal { rackets map { _.area() } }
```

```
val leftWall = ball.changed && { _.x < 0 }
val rightWall = ball.changed && { _.x > maxX }
```

```
val xBounce = {
  val ballInRacket = Signal { areas() exists { _ contains ball() } }
  val collisionRacket = ballInRacket.changedTo True
  leftWall || rightWall || collisionRacket
  val yBounce = ball.changed &&
    { ball => ball.y < 0 || ball.y > maxY }
```

```
val speed = {
  val x = xBounce.toggle (initSpeed.x, -initSpeed.x)
  val y = yBounce.toggle (initSpeed.y, -initSpeed.y)
  Signal { Point(x(), y()) }
```

```
val score = {
  val leftPoints = rightWall.iterate(0) { _, +1 }
  val rightPoints = leftWall.iterate(0) { _, +1 }
  Signal { leftPoints() + "-" + rightPoints() }
```

```
areas observe / undataArea(areas) =>
  ball observe / undataBall(ball) =>
  score observe / updateScore(score) }
```

```
clients observe / clients =>
  undataArea(areas) =>
  undataBall(ball) =>
  updateScore(score) }
```

```
def receive = {
  case UndataArea(areas) => UI.areas set areas
  case UndataBall(ball) => UI.ball set ball
  case UpdateScore(score) => UI.score set score }
```

```
server ! AddPlayer
}
```

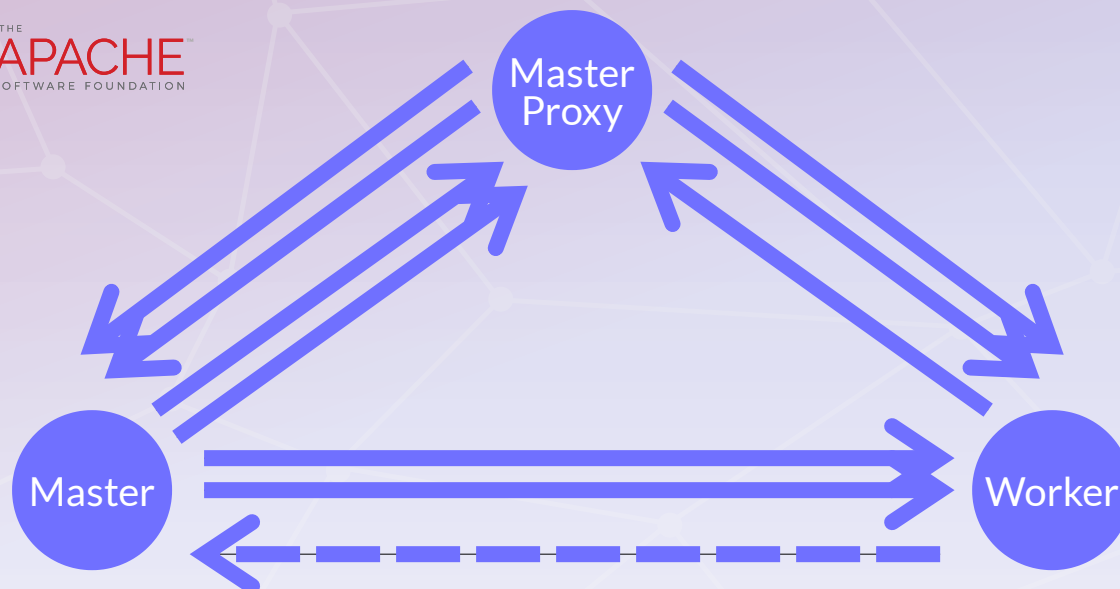
multi-user support  
distribution

# Gearpump Real-Time Streaming Engine



components with  
placement types

no need to manually  
maintain architecture



```
trait MasterProxy extends Peer { type Tie <: Multiple[Master] with Multiple[Worker] }  
trait Worker extends Peer { type Tie <: Single[MasterProxy] with Optional[Master] }  
trait Master extends Peer { type Tie <: Multiple[MasterProxy] with Multiple[Worker] }
```





# Flink

## Multiple modules

- CheckpointResponder
- KvStateRegistryListener
- PartitionProducerStateChecker
- ResultPartitionConsumableNotifier
- TaskManager
- TaskManagerActions

Eliminated 23 non-exhaustive pattern matches  
and 8 type casts

```
class TaskManagerGateway {
  def disconnectFromJobManager(instanceId: InstanceID, cause: Exception, mgr: Remote[TaskManager]) = {
    mgr ! Disconnect(instanceId, cause)
  }

  def stopCluster(applicationStatus: ApplicationStatus, message: String, mgr: Remote[TaskManager]) = {
    mgr ! StopCluster(applicationStatus, message)
  }

  def submitTask(tdd: TaskDeploymentDescriptor, mgr: ActorRef) = {
    mgr ! SubmitTask(tdd)
  }

  def cancelTask(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    mgr ! CancelTask(executionAttemptID)
  }

  def triggerCheckpointBarrier(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    mgr ! TriggerCheckpointBarrier(executionAttemptID)
  }

  def notifyCheckpointComplete(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    mgr ! NotifyCheckpointComplete(executionAttemptID)
  }

  def requestTaskManagerLog(logTypeRequest: LogTypeRequest, mgr: ActorRef) = {
    mgr ! RequestTaskManagerLog(logTypeRequest)
  }
}
```

```
class TaskManager extends Actor {
  def receive = {
    case Disconnect(instanceIdToDisconnect, cause) =>
      if (instanceIdToDisconnect.equals(instanceID)) {
        handleJobManagerDisconnect(JobManager requested disconnect: " +
          cause.getMessage())
      } else {
        log.debug("Received disconnect message for wrong instance id " +
          instanceIDToDisconnect)
      }

    case StopCluster(applicationStatus, message) =>
      log.info("Stopping TaskManager with final application status " +
        applicationStatus and diagnostics: $message")
      shutdown()

    case RequestTaskManagerLog(requestType) =>
      case Some(l) =>
        handleRequestTaskManagerLog(requestType, currentJobManager.get) match {
          case Left(message) => sendBack(message)
          case Right(message) => sendBack(message)
        }
      case None =>
        log.status(Status.Failure(new IOException(
          "No log service available. Cannot upload TaskManager logs.")))

    case CancelTask(executionID) =>
      val task = runningTasks.get(executionID)
      if (task != null) {
        task.cancelExecution()
        sendBack(DecorateMessage(Acknowledge.get()))
      } else {
        log.debug("Cannot find task to stop for execution $executionID")
        sender ! DecorateMessage(Status.Failure(t))
      }

    case TriggerCheckpointBarrier(jobId, taskExecutionId, checkpointId, timestamp,
      checkpointOptions) =>
      log.debug("Receiver TriggerCheckpoint $checkpointId@timestamp " +
        s"for task $taskExecutionId")
      val task = runningTasks.get(taskExecutionId)
      if (task != null) {
        task.triggerCheckpointBarrier(checkpointId, timestamp, checkpointOptions)
      } else {
        log.debug("TaskManager received a checkpoint request " +
          s"for unknown task $taskExecutionId.")
      }

    case NotifyCheckpointComplete(jobId, taskExecutionId, checkpointId, timestamp) =>
      log.debug("Receiver ConfirmCheckpoint $checkpointId@timestamp " +
        s"for task $taskExecutionId.")
      val task = runningTasks.get(taskExecutionId)
      if (task != null) {
        task.notifyCheckpointComplete(checkpointId)
      } else {
        log.debug("TaskManager received a checkpoint confirmation " +
          s"for unknown task $taskExecutionId.")
      }
  }
}
```

```
@MultiTrait trait TaskManagerGatewayClusterTask {
  trait JobManager extends Peer { type Tie <: Multiple[TaskManager] }
  trait TaskManager extends Peer { type Tie <: Single[JobManager] }

  def disconnectFromJobManager(instanceId: InstanceID, cause: Exception,
    mgr: Remote[TaskManager]) = {
    mgr ! Disconnect(instanceId, cause)
  }

  def stopCluster(applicationStatus: ApplicationStatus, message: String,
    mgr: Remote[TaskManager]) = {
    mgr ! StopCluster(applicationStatus, message)
  }

  def submitTask(tdd: TaskDeploymentDescriptor, mgr: ActorRef) = {
    mgr ! SubmitTask(tdd)
  }

  def cancelTask(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    mgr ! CancelTask(executionAttemptID)
  }

  def triggerCheckpointBarrier(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    mgr ! TriggerCheckpointBarrier(executionAttemptID)
  }

  def notifyCheckpointComplete(executionAttemptID: ExecutionAttemptID, mgr: ActorRef) = {
    mgr ! NotifyCheckpointComplete(executionAttemptID)
  }

  def requestTaskManagerLog(logTypeRequest: LogTypeRequest, mgr: ActorRef) = {
    mgr ! RequestTaskManagerLog(logTypeRequest)
  }
}
```

```
@MultiTrait trait TaskManagerGatewayPartitionChecking {
  trait JobManager extends Peer { type Tie <: Multiple[TaskManager] }
  trait TaskManager extends Peer { type Tie <: Single[JobManager] }

  def updatePartitionInfo(executionAttemptID: ExecutionAttemptID,
    partitionInfos: java.lang.Iterable[PartitionInfo], mgr: Remote[TaskManager]) = {
    mgr ! UpdatePartitionInfo(executionAttemptID, partitionInfos)
  }

  def failPartition(executionAttemptID: ExecutionAttemptID, mgr: Remote[TaskManager]) = {
    mgr ! FailPartition(executionAttemptID)
  }

  def notifyCheckpointComplete(executionAttemptID: ExecutionAttemptID,
    jobId: JobID, checkpointId: Long, timestamp: Long, mgr: Remote[TaskManager]) = {
    mgr ! NotifyCheckpointComplete(executionAttemptID, jobId, checkpointId, timestamp)
  }

  def triggerCheckpointBarrier(executionAttemptID: ExecutionAttemptID,
    jobId: JobID, checkpointId: Long, timestamp: Long, checkpointOptions: CheckpointOptions,
    mgr: Remote[TaskManager]) = {
    mgr ! TriggerCheckpointBarrier(executionAttemptID, jobId, checkpointId, timestamp,
      checkpointOptions)
  }

  def requestTaskManagerLog(logTypeRequest: LogTypeRequest, mgr: Remote[TaskManager]) = {
    mgr ! RequestTaskManagerLog(logTypeRequest)
  }
}
```



# Apache Flink Stream Processor



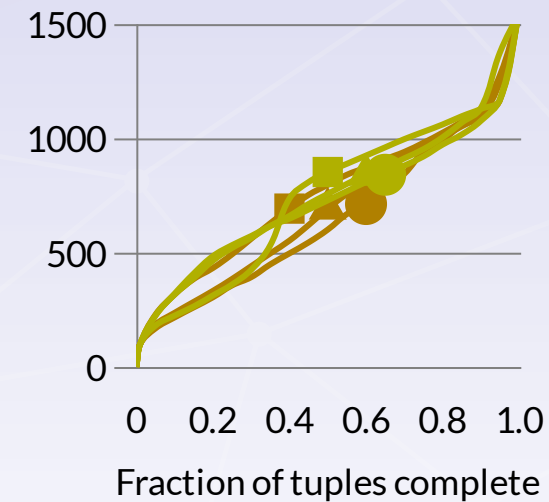
Cloud Deployment **Amazon EC2**  
Yahoo Streaming Benchmark

Latency



■ Flink  
■ ScalaLoci Flink

Cumulative Distribution



● Flink, 4 workers  
▲ Flink, 6 workers  
■ Flink, 8 workers  
● ScalaLoci Flink, 4 workers  
▲ ScalaLoci Flink, 6 workers  
■ ScalaLoci Flink, 8 workers



## Distributed System Development with SCALALOCi

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Distributed applications are traditionally developed as separate modules, often in different languages. These modules react to events, like user input, and in turn produce new events for the other modules. Such a development process requires time-consuming integration. Manual implementation of communication forces programmers to deal with low-level details. The combination of the two results in obscure distributed systems, which are hard to maintain among multiple modules, hindering reasoning about the system as a whole.

The SCALALOCi distributed programming language addresses these issues with a cohesive design. It introduces placement types that enables reasoning about distributed data flows, supporting multiple software architectures via dedicated language features and abstracting over low-level communication details. As we show, SCALALOCi simplifies developing distributed systems, reduces error-prone code, and favors early detection of bugs.

CCS Concepts: • **Software and its engineering** → **Distributed programming languages**; • **Theory of computation** → *Distributed computing models*;

Additional Key Words and Phrases: Distributed Programming, Multitier Programming, Reactive Programming, Placement Types, Scala

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Fault Tolerance


Dynamic Topologies

Design Metrics

Microbenchmarks

Multiple Backends

Formalization



## ScalaLoci

Research and development of language abstractions for distributed applications in Scala

### Coherent

Implement a cohesive distributed application in a single multitier language


### Comprehensive

Freely express any distributed architecture

### Safe

Enjoy static type-safety across components

### 1




#### Specify Architecture

Define the architectural relation of the components of the distributed system

```
trait Server extends Peer {  
  type Tie = Multiple[Client]  
}  
  
trait Client extends Peer {  
  type Tie = Single[Server]  
}
```

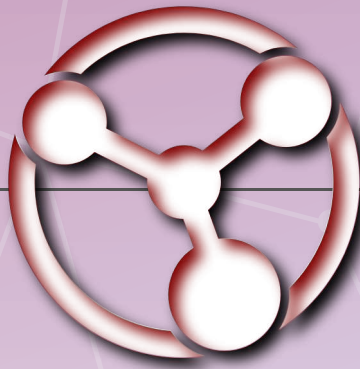
### 2



#### Specify Placement

Control where data is located and computations are executed

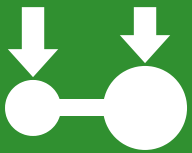
```
val items = placed[Server] {  
  getCurrentItems()  
}  
  
val ui = placed[Client] {  
  new UI  
}
```



# ScalaLoci



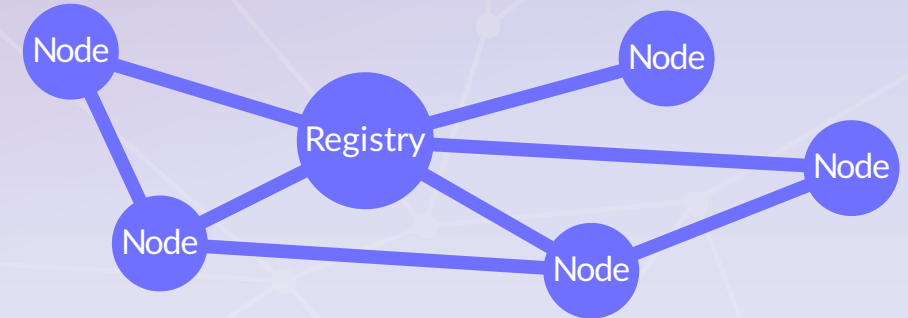
Generic Distributed Architectures



Placement Types



Multitier Event Streams



Value on Peer

